



Accelerated photosynthesis routine in LPJmL4

Jenny Niebsch¹, Werner von Bloh², Kirsten Thonicke², and Ronny Ramlau¹ ¹RICAM, Altenbergerstr. 69, 4040 Linz, Austria ²Potsdam Institute for Climate Impact Research (PIK), Member of the Leibniz Association, 14412 Potsdam, Germany **Correspondence:** Jenny Niebsch (jenny.niebsch@oeaw.ac.at)

Abstract. The increasing impacts of climate change require strategies for climate adaptation. Dynamic Global Vegetation Models (DGVMs) are one type of multi-sectorial impact models with which the effects of multiple interacting processes in the terrestrial biosphere under climate change can be studied. The complexity of DGVMs is increasing as more and more processes, especially for plant physiology, are implemented. Therefore, there is a growing demand for increasing the com-

5 putational performance of the underlying algorithms as well as ensuring their numerical accuracy. One way to approach this issue is to analyse the routines which have the potential for improved computational efficiency and/or increased accuracy when applying sophisticated mathematical methods.

In this paper, the Farquhar-Collatz photosynthesis model under water stress as implemented in the Lund-Potsdam-Jena managed Land DGVM (4.0.002) was examined. We found that the numerical solution of a nonlinear equation, so far solved with the

- 10 Bisection method, could be significantly improved by using Newton's method instead. The latter requires the computation of the derivative of the underlying function which is presented. Model simulations show a significant lower number of iterations to solve the equation numerically and an overall run time reduction of the model of about 16 % depending on the chosen accuracy. The Farquhar-Collatz photosynthesis model forms the core component in many DGVMs and land-surface models. An update in the numerical solution of the nonlinear equation can therefore be applied to similar photosynthesis models. Furthermore, this
- 15 exercise can serve as an example for improving computationally costly routines while improving their mathematical accuracy.

1 Introduction

Climate change is increasingly affecting the world we live in and that in turn affects nature's contribution to our livelihoods, (Pörtner et al., 2022). Estimating the extent and impacts of climate change has become more and more urgent over the last couple of decades. Earth System models as well as impact models are used to develop strategies for climate adaptation and

- 20 mitigation to achieve the Paris climate accord, (Masson-Delmotte et al., 2021), (Pörtner et al., 2022). Climate change affects vegetation dynamics, biodiversity, water and biogeochemical cycles which could reduce the biosphere's capacity to absorb carbon from the atmosphere in the future. Dynamic Global Vegetation Models (DGVMs) are applied to study the net effects of multiple interacting processes that affect carbon sequestration (photosynthesis) and storage (in biomass and soil), see (Prentice et al., 2007). It shows the demand for reliable and consistent model projections which require continuous work on reducing
- 25 model uncertainty. While increasing complexity of the models by including more and more processes in DGVMs has been matched by increasing high-performance computing capabilities over the past decades, little has been invested in identifying





and optimizing computationally intensive routines in the model (Reichstein et al., 2019). These routines often have a long model history as they frequently belong to the core routines stemming from the very first model version. This includes, e.g., the physiological modelling core of simulating photosynthesis in connection with atmospheric water demand or plant-water
30 stress. The photosynthesis model is based on the Farquhar approach implemented in first global biome models by Haxeltine and Prentice (1996a) from which DGVMs evolved later on, (Prentice et al., 2007). Today, this type of photosynthesis module forms the core of the majority of DGVMs, see e.g., (Smith et al., 2001, 2014; Krinner et al., 2005).

In order to apply the model to the global land surface it is not anymore sufficient to use faster or larger computing infrastructure or try to parallelise the code as in von Bloh et al. (2010). It rather requires the evaluation of the underlying algorithm structure of the code, and in particular the used numerical methods. Replacing 'old' numerical algorithms by modern methods

- 35 structure of the code, and in particular the used numerical methods. Replacing 'old' numerical algorithms by modern methods will result in a significantly better run-time performance while simultaneously maintaining or even increasing the accuracy of the method. We quantified the runtime required by each submodule (or routine) of the LPJmL DGVM and found that the repeated execution of the photosynthesis routine demands a big fracture of the computational time.
- To illustrate our approach, our goal was to improve the computational efficiency of DGVMs by accelerating the photosyn-40 thesis module under water stress conditions using the Lund-Potsdam-Jena DGVM, (Schaphoff et al., 2018a, b), as an example. A key ingredient in the modelling of photosynthesis is the determination of the ratio λ between intracellular and ambient CO₂ concentration. Mathematically, λ is computed as a zero of a nonlinear equation $f(\lambda) = 0$, which has been so far solved by a simple bisection algorithm. We expected to improve the computational efficiency by applying one of the more sophisticated solution methods, namely Regula falsi, secant and Newton's method. In this technical paper, we describe testing all three meth-
- 45 ods, but found that only with Newton's method the computational efficiency was significantly improved.

We start with a short description of the different mathematical methods to find the zeros of a general nonlinear continuous function *f* and their advantages and disadvantages. Afterwards we introduce the relevant function *f* from the photosynthesis module and calculate its derivative. We then compare the performance of Newton's algorithm and bisection in terms of the number of iterations and the computational time that is necessary to achieve a given accuracy. Finally, we benchmark the updated LPJmL version to show that the simulated vegetation dynamics as well as storage and fluxes of carbon and water remain robust.

2 Solution of nonlinear equations

The computation of the ratio λ between intracellular and ambient CO₂ concentration requires to compute the zero of a function 55 $f(\lambda)$. In most cases, this task cannot be solved analytically but requires a numerical approach, mostly based on iterative methods. Given a nonlinear continuous function $f : \mathbb{R} \to \mathbb{R}$, we want to find the zero(s) x_s of this function within a certain interval [a,b]. While bisection, regula falsi and secant method are very simple to implement, Newton's method requires the computation of the derivative of f, which will be provided for the photosynthesis equation described in Sub-Section 3.2. Here, the computational efficiency is determined by the speed of convergence. To compare the methods with respect to the





60 speed of convergence we define the order of convergence: Let x_s be a zero of f found by computing a sequence (x_k) of approximate solutions via an iteration scheme. The iteration method has the order of convergence p if

$$\lim_{k \to \infty} \sup_{k \to \infty} \frac{\|x_{k+1} - x_s\|}{\|x_k - x_s\|^p} = K$$
(1)

with $0 < K < \infty$ and K < 1 for p = 1. Thus a high order of convergence implies a fast convergence which on the other hand means fewer iteration steps. Numerically, the iteration is stopped either if the function value $f(x_k)$ of the iterate x_k is almost zero, i.e., less than a given accuracy y_{acc} , or if the iterate itself changes less than a given accuracy $|x_k - x_{k-1}| < x_{acc}$. Let us introduce some of the methods in the following subsections, see Schwarz (1988) for details.

2.1 Bisection

65

For bisection we have to choose [a,b] such that f(a) ⋅ f(b) < 0, i.e. f(a) and f(b) have different signs. We compute the midpoint of the interval x_m = a+b/2 and its function value f(x_m). If |f(x_m)| < y_{acc} the search is complete, if not we check
70 if f(a) ⋅ f(x_m) < 0. If the latter is the case, x_s has to be in the interval [a, x_m], otherwise in [x_m,b]. We repeat this bisection until either |f(x_k)| < y_{acc} or |x_k - x_{k-1}| < x_{acc}. This method always converges but slowly with convergence order p = 1, i.e., linear convergence.

2.2 Regula falsi

For the regula falsi method, we also need to choose a, b such that $f(a) \cdot f(b) < 0$. Instead of the midpoint of [a, b] we compute 75 the next iterate x_1 for an approximation of x_s by computing the zero of the linear function through the points (a|f(a)) and (b|f(b)). Again we check if $|f(x_1)| < y_{acc}$ and abort or check if $f(a) \cdot f(x_1) < 0$ and repeat this procedure either with $[a, x_1]$ or $[x_1, b]$. Convergence is always assured and also linear, i.e., p = 1.

2.3 Secant method

The secant method only differs from the regula falsi in that the starting values $a = x_0$ and $b = x_1$ do not have to fulfill the 80 condition $f(a) \cdot f(b) < 0$. The next iterate is computed by

$$x_{k+1} = x_k - f(x_k) \frac{x_k - x_{k-1}}{f(x_k) - f(x_{k-1})}.$$
(2)

This method can fail to converge depending on the starting values. If the method converges, it does so with order p = 1,618. Since the conditions on the starting values to ensure convergence depend on the knowledge of x_s , in practise a and b still have to fulfill the condition $f(a) \cdot f(b) < 0$.

85 2.4 Newton's method

Newton's method starts at an arbitrary approximation x_0 of x_s and uses the tangent of the function f at $(x_0, f(x_0))$ to compute the next iterate x_1 as the zero of the tangent. This is repeated, thus the next iterate is always computed from the previous one





by

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)},$$
(3)

90 provided that $f'(x_k) \neq 0$. The method belongs to the class of fixed point iterations because the computation of the next iterate depends on the previous iterate only. If f is three times differentiable on [a,b] and $f'(x_s) \neq 0$ then there exists an interval $I = [x_s - \delta, x_s + \delta]$ such that f is a contraction on I. It implies that for every start value from I, the method converges at least with order p = 2, (Schwarz, 1988). We remark that the gain in convergence speed has to be weighted against the time it takes to compute the derivative of f.

95 **3** Application to the problem

We now analyse the difference in speed of convergence between the bisection and Newton's method when applied to the optimization equation of the photosynthesis routine of the LPJmL DGVM.

3.1 Definition of the function f

In presenting the function $f(\lambda)$, we follow the nomenclature of Schaphoff et al. (2018a), which contains a detailed description 100 of the derivation of this function. A list of the used symbols is given in Appendix A. We want to solve

$$0 = f(\lambda) = A_{nd}(\lambda) + \left(1 - \frac{dayl}{24}\right) R_{leaf} - \frac{p_a(g_c - g_{min})}{1.6}(1 - \lambda).$$
(4)

With $A_{nd}(\lambda) = A_{gd}(\lambda) - R_{leaf}$ and using the abbreviation $C_{pg} = \frac{p_a(g_c - g_{min})}{1.6}$, we have a shorter version

$$0 = f(\lambda) = A_{gd}(\lambda) - \frac{dayl}{24} R_{leaf} - C_{pg}(1-\lambda).$$
(5)

The second summand does not depend on λ , whereas $A_{qd}(\lambda)$ has a more complex representation:

105
$$A_{gd}(\lambda) = \frac{dayl}{2\theta} \left[J_E(\lambda) + J_C(\lambda) - \sqrt{(J_E(\lambda) + J_C(\lambda))^2 - 4\theta J_E(\lambda) J_C(\lambda)} \right]$$
 (6)

with

$$J_E(\lambda) = C_1(\lambda) \frac{APAR}{dayl},\tag{7}$$

$$J_C(\lambda) = C_2(\lambda) V_m.$$
(8)

Setting the internal partial pressure $p_i = \lambda p_a$ and using another abbreviation $C_K := K_c (1 + \frac{[O_2]}{K_O})$, we have

110
$$C_{1}(\lambda) = \begin{cases} T_{stress} \alpha_{C3} \frac{\lambda p_{a} - \Gamma_{*}}{\lambda p_{a} + (2)\Gamma_{*}} & \text{for C3- Photosynthesis} \\ T_{stress} \alpha_{C4} \frac{\lambda}{\lambda_{max_{C4}}} & \text{for C4- Photosynthesis} \end{cases}$$
(9)
$$C_{2}(\lambda) = \begin{cases} \frac{\lambda p_{a} - \Gamma_{*}}{\lambda p_{a} + C_{K}} & \text{for C3- Photosynthesis} \\ 1 & \text{for C4- Photosynthesis.} \end{cases}$$
(10)





Here, T_{stress} is the temperature stress function defined as

$$T_{stress} = \frac{1 - 0.01e^{T_3(T_d - T_4)}}{1 + e^{T_1(T_2 - T_d)}} \tag{11}$$

with T_d as the daily air temperature and T_1 to T_4 being PFT-specific temperature parameters, (Sitch et al., 2000). LPJmL 115 simulates vegetation dynamics for 10 so-called Plant Functional Types (PFTs); we provide the parameter values used for T_1 to T_4 in Appendix A, table A2, for the PFT types from Schaphoff et al. (2018a).

3.2 Derivative of f

The derivative f' of f is given by

$$f'(\lambda) = A'_{gd}(\lambda) + C_{pg}.$$
(12)

120 Applying sum, chain, and product rule of differentiation we get

$$A'_{gd}(\lambda) = \frac{dayl}{2\theta} \left[J'_E + J'_C - \frac{[J_E + J_C][J'_E + J'_C] - 2\theta[J'_E J_C + J_E J'_C]}{\sqrt{(J_E + J_C)^2 - 4\theta J_E J_C}} \right]$$
(13)

with

$$J'_E(\lambda) = C'_1(\lambda) \frac{APAR}{dayl}, \tag{14}$$

$$J_C'(\lambda) = C_2'(\lambda)V_m \tag{15}$$

125 and with the quotient rule

$$C_{1}'(\lambda) = \begin{cases} T_{stress} \alpha_{C3} \frac{2(3)p_{a}\Gamma_{*}}{(\lambda p_{a}+(2)\Gamma_{*})^{2}} & \text{for } C_{3}\text{- Photosynthesis} \\ \frac{T_{stress} \alpha_{C4}}{\lambda_{max_{C4}}} & \text{for } C_{4}\text{- Photosynthesis} \end{cases}$$
(16)

$$C_{2}'(\lambda) = \begin{cases} \frac{p_{a}(C_{K}+\Gamma_{*})}{(\lambda p_{a}+C_{K})^{2}} & \text{for } C_{3}\text{- Photosynthesis} \\ 0 & \text{for } C_{4}\text{- Photosynthesis.} \end{cases}$$
(17)

We describe the consequent changes in the model code which were required to implement the computation of the derivative $fcnd(\lambda)$ in the Appendix B.

130 4 Numerical performance and discussion

We have tested the different methods in the routine regarding computational time and number of iterations for given accuracy x_{acc} . There was no significant speed-up with the secant and regula falsi method. Hence, we concentrated on the comparison of Bisection and Newton's method and describe the outcome in this section.

In a first test, the LPJmL model was run over 120 simulation years and the number of iterations in the Bisection and Newton's
routine was counted and averaged over all grid cells and one year (Figure 1). For x_{acc} = 0.01 this number was about 3 for Newton's method and 7 for Bisection (dotted lines in Figure 1). When x_{acc} was set to 0.001 the number of iterations with





Newton's method increased only slightly whereas the Bisection method needed 9 to 10 iterations (solid lines in Figure 1). Until now, the bisection algorithm used 10 as the maximal number of iterations. Using maximum 10 iterations fits to the interval width of $2^{-10} \approx 0.001$, our accuracy measure x_{acc} . Increasing the maximum number of iterations had no effect on the number of required iterations. We conclude that Newton's method reduces the necessary number of iteration to a third.

- 140 of required iterations. We conclude that Newton's method reduces the necessary number of iteration to a third. In a next step, a spin-up run of LPJmL over 5000 simulation years was conducted to compare the time performance using both routines. Usually, LPJmL simulation experiments start from bare ground, i.e. initial vegetation conditions are not prescribed. Therefore, a spin-up run is used to bring all vegetation and soil carbon pools into equilibrium with climate. For the usually implemented accuracy $x_{acc} = 0.1$ the computation time for 5000 years was about 5250 s in both cases. This means that the
- 145 advantage of Newton's method in terms of iteration numbers is levelled by the additional time for computing the derivative of f. For $x_{acc} = 0.01$, the Bisection method needed 6700 s, while Newton's method 5600 s. Thus a reduction of about 16% in time could be observed. It implies that with almost the same amount of time (5250 s vs. 5600 s) a higher accuracy can be achieved with Newton's method (Figure 2). While the accuracy y_{acc} does not increase significantly for the Bisection method for $x_{acc} = 0.001$, we gain 2 orders of magnitude increase in y_{acc} for the Newton's method. As a result, a change of x_{acc} from
- 150 0.1 to 0.01 will be permanently implemented in the LPJmL model for future model applications. We expect that with the implementation of new model developments that affect the photosynthesis module (e.g., nutrient limitation from nitrogen and leaf temperatures) an efficient and increased model accuracy (y_{acc}) for finding the zero of $f(\lambda)$ will be even more important. It can be expected that the computation time for the Bisection method would increase substantially, while increasing only moderately for Newton's method.

155



Figure 1. Average number of iteration for Bisection (upper lines, blue) and Newton (lower lines, red) for accuracy $x_{acc} = 0.01$ (dotted) and 0.001 (solid)

In order to check if the implementation of Newton's method is robust for all important model variables, we performed a transient simulation with the LPJmL model starting from the spin-up and covering the years 1901-2000. Model configuration and







Figure 2. Mean decadic logarithm of the accuracy y_{acc} for Bisection (upper lines, blue) and Newton (lower lines, red) for accuracy $x_{acc} = 0.01$ (dotted) and 0.001 (solid). The dashed-dotted line shows the accuracy of the original version of LPJmL.

input data are as in Schaphoff et al. (2018a). We compared the main diagnostic variables of the published LPJmL4.0 version against the version using the Newton's Method (see Appendix C). We found that most global diagnostic variables related to

- 160 fluxes and storage of carbon and water had differences of $< \pm 1.0\%$, including total vegetated area. Only marginal changes (+3 gC per m² and month) in net primary productivity (NPP), heterotrophic respiration and evaporation are seen mainly in Europe and southern as well as southeastern Asia. The reductions in carbon storage in litter and soil are very small and apply only to the boreal zone across the northern hemisphere and central Europe (compare spatial maps of carbon and water variables in Appendix C).
- 165 The photosynthesis module is also applied to the crop functional types and managed grassland within LPJmL4.0. Therefore, sawing dates, crop productivity and harvest are among the simulated variables. Comparing both model versions in the model benchmark, we found that global harvest changed for a number of crops. Rainfed and irrigated rice increased by 5% and 8%, respectively, mainly in India and southeast Asia. Harvest of rainfed temperate cereals increased by < 1.0%, mainly found in central Europe. Harvest of irrigated temperate cereals (incl. wheat) increased by 4.5%, which mainly applied to India as well.
- 170 Harvest of irrigated and rainfed soybean increased by 2.3% and 1.5% globally, the differences are mainly found in the US and Brazil. All other crop functional types had marginal to zero changes in global productivity as well as simulated harvest (see Table in Appendix C).

For all global carbon pools (vegetation and soil) and carbon (GPP, heterotrophic respiration and fire emissions) as well as
water fluxes (transpiration and runoff) we found no difference in the temporal changes in the transient simulation over the 20th century. All variables showed similar, if not identical dynamics (see time series' graphs in Appendix C). Small changes were found in the fractional coverage of plant functional types, i.e. most differences were negligible. The fractional coverage of Temperate broadleaved summergreen trees increased by 4.8% globally, which mainly applies to Europe, northeastern US





and parts of China. Increases in temperate C_3 grasses are found in the boreal zone, summing up to 4.8% globally. Marginal changes of < 0.5% per grid cell are found for all other PFTs which imply small adjustments in vegetation composition in these vegetation zones (see difference maps in Appendix C). Comparisons using flux tower measurements on carbon and water fluxes as well as discharge data showed no differences so that we can conclude that also for these variables the results are robust (data not shown). We can therefore conclude that the LPJmL results were robust before, but are now achieved due to improved accuracy of the photosynthesis routine.

185

5 Conclusions

The computational load of Dynamic Global Vegetation Models, caused by increased complexity of the modelling processes, has been so far counteracted by the used high performance computing systems. However, more recently it has become clear that updates in computing infrastructure are not sufficient anymore. Consequently, we proposed to carefully evaluate the algorithmic

- 190 structure of DGVMs and identify and update routines that can benefit from the use of modern mathematical methods. As a showcase, we investigated the photosynthesis model in the LPJmL DGVM. Specifically, we investigated the computation of the ratio λ between intracellular and ambient CO₂, which is obtained as the zero of a function *f*. We proposed to replace the so far used bisection method by a Newton method, which is known to converge significantly faster. We carefully compared the model performance of the published LPJmL4.0 version with the version developed in this study and found that the model
- 195 performance is robust. Using a more sophisticated mathematical method in the photosynthesis module allowed for a higher precision in the computation of λ and resulted in slightly increased productivity in continental and mountainous areas. We think that the new results are more accurate than the previous version due to the higher accuracy of the Newton method visible in Figure 2. With the currently implemented accuracy bounds, the run-time of the model with the Newton routine implemented is about 16% lower than the old version. This advantage will be much more prominent if the complexity of the model is further extended or if more accurate modelling results are required. Consequently, the Newton based routine will be implemented in
- the LPJmL model. Additionally we believe that the Newton method can also be applied to photosynthesis modules in other DGVMs and increase model accuracy and/or computational efficiency.

Code and data availability. The model code is available at https://doi.org/10.5281/zenodo.6644541 .





Appendix A: Parameters in photosynthesis

A_{nd}	daily net photosynthesis
dayl	day length
R_{leaf}	leaf respiration
p_a	ambient partial pressure
g_c	canopy conductance
g_{min}	PFT-specific minimum canopy conductance
A_{gd}	daily gross photosynthesis
θ	co-limitation (shape) parameter
J_E	light limited photosynthesis rate
J_C	Rubisco limited photosynthesis rate
APAR	absorbed photosynthetically active radiation
V_m	maximum Rubisco capacity
K_C	Michaelis constant for CO_2
$[O_2]$	O_2 partial pressure
K_O	Michaelis constant for O_2
T_{stress}	Temperature stress function limiting photosynthesis
	at low and high temperatures
α_{C3}	intrinsic quantum efficiencies for CO_2 uptake in C_3 plants
α_{C4}	intrinsic quantum efficiencies for CO_2 uptake in C_4 plants
Γ_*	carbone dioxide compensation point
λ_{maxC4}	maximum ratio of intracellular to ambient CO_2 for C_4 -photosynthesis

Table A1.

General parameters used in the photosynthesis routine. PFT - Plant functional type





Plant Functional Type (PFT)		T_2	T_3	T_4
Tropical broadleaved evergreen tree		25.0	30.0	55.0
Tropical broadleaved raingreen tree		25.0	30.0	55.0
Temperate needleleaved evergreen tree		20.0	30.0	42.0
Temperate broadleaved evergreen tree	-4.0	20.0	30.0	42.0
Temperate broad-leaved summergreen tree		20.0	25.0	38.0
Boreal needle-leaved evergreen tree		15.0	25.0	38.0
Boreal needle-leaved summergreen tree		15.0	25.0	38.0
Polar C_3 grass	-4.0	10.0	30.0	45.0
Temperate C_3 grass	-4.0	10.0	30.0	45.0
Tropical C_4 grass	6.0	20.0	45.0	55.0

Table A2.

PFT-specific parameter for temperature stress function (eq.12) in °C. PFT types as in Schaphoff et al. (2018a)

205 Appendix B: Programming

To implement Newton's method in the LPJmL code, changes had to be made in the functions photosynthesis.c, gp_sum.c and water_stressed.c. (separate file)

New function newton.c: see source code in a separate file.

Remark

210 The function photosynthesis.c within LPJmL computes the value $A_{nd}(\lambda) + \left(1 - \frac{dayl}{24}\right)R_{leaf}$ for a given λ . In the function water_stressed.c the function fcn(λ) is defined as $fcn(\lambda) = C_{pg} * (1 - \lambda) - photosythesis(lambda)$, i.e. fcn = -f. In order to use Newton's Method we have to compute not only $fcn(\lambda)$ but also its derivative $fcnd(\lambda) = -f'(\lambda)$.

Appendix C: Benchmark results





215

LPJmL Benchmark

Actual vegetation Author: Werner von Bloh Date: 27.04.2022 Benchmark run: newton_e3/output/ Run: bisect_e3/output/ Description: LPJ Benchmark 2022-04-27

Global sums: Veg. incl. LU 1991-2000

Parameter	Lit. estimates	Bm. Run	Run	Diff. abs.	Diff %
Vegetation carbon [GtC]	460 - 660 (1 2 3)	595.9	596.2	0.231	0.039
Total soil carbon density	2376 - 2456 (4) - 1567	1862	1862	-0.08	-0.004
[GtC]	(5), 1395 (6)	1002	1002	0.00	0.001
Litter carbon [GtC]	NA	151.3	151.4	0.116	0.077
Fire carbon emission	2.14 (1.6 Nat.Fire) (7.	3.108	3.109	0.001	0.036
[GtC/vear]	8, 9, 10)				
Establishment flux	NA	0.161	0.161	0	-0.002
[GtC/year]					
Area All natural	NA	7767	7767	-0.119	-0.002
vegetation [M ha]					
Area Tropical	NA	1180	1179	-0.237	-0.02
broadleaved evergreen					
tree [M ha]					
Area Tropical	NA	1280	1280	0.448	0.035
broadleaved raingreen					
tree [M ha]					
Area Temperate	NA	364	360.8	-3.166	-0.87
needleleaved evergreen					
tree [M ha]					
Area Temperate	NA	322	321.5	-0.467	-0.145
broadleaved evergreen					
tree [M ha]					
Area Temperate	NA	136	142.5	6.517	4.792
broadleaved					
summergreen tree [M ha]					
Area Boreal needleleaved	NA	429.2	426.8	-2.393	-0.558
evergreen tree [M ha]					
Area Boreal broadleaved	NA	916.8	919.6	2.814	0.307
summergreen tree [M ha]					

1





		Bm.			
Parameter	Lit. estimates	Run	\mathbf{Run}	Diff. abs.	Diff $\%$
Area Boreal needleleaved	NA	378.3	380.7	2.398	0.634
summergreen tree [M ha]					
Area Tropical c4 grass	NA	893.2	890.6	-2.573	-0.288
[M ha]					
Area Temperate c3 grass	NA	535.7	545.2	9.472	1.768
[M ha]					
Area Polar c3 grass [M	NA	1332	1320	-12.93	-0.971
ha]					
NPP [GtC/year]	$\begin{array}{c} 66.05 \ (11), \ 62.6 \ (2), \\ 49.52 \ - \ 59.74 \ (12) \end{array}$	62.81	62.87	0.064	0.102
Heterotrophic	NA	50.78	50.83	0.044	0.086
respiration [GtC/year]					
Evaporation [10	NA	9.644	9.661	0.017	0.173
km3/year]					
Transpiration [10	NA	47.83	47.82	-0.011	-0.024
km3/year]					
Interception [10	NA	7.914	7.912	-0.002	-0.024
km3/year]					
Runoff [10 km3/year]	NA	54.3	54.23	-0.064	-0.118
Harvested carbon rainfed	524.08(13)	458.5	462.6	4.106	0.895
tece [Mt DM/year]					
Harvested carbon rainfed	492.66(13)	125.2	131.5	6.304	5.035
rice [Mt DM/year]					
Harvested carbon rainfed	498.33(13)	434.9	434.8	-0.07	-0.016
maize [Mt DM/year]					
Harvested carbon rainfed	NA	126.3	128.1	1.87	1.481
soybean [Mt DM/year]					
Harvested carbon	524.08(13)	156.7	163.7	7.038	4.493
irrigated tece [Mt					
DM/year]	(
Harvested carbon	492.66(13)	206.4	223	16.64	8.062
irrigated rice [Mt					
DM/year]	100.00 (10)	150.1	450.4	0.000	0.001
Harvested carbon	498.33(13)	153.1	153.1	-0.002	-0.001
irrigated maize [Mt					
DM/year]	27.4	10.00	10.0	0.000	2 222
Harvested carbon	NA	12.03	12.3	0.268	2.229
irrigated soybean [Mt					
DM/year]	27.4	0.011	0.045	0.001	0.10
tree cover fraction [-]	NA	0.644	0.645	0.001	0.12

 Olson et al. 1985, (2) Saugier et al. 2001, (3) WBGU 1998, (4) Batjes et al. 1996, (5) Eswaran et al. 1993, (6) Post et al. 1982, (7) Seiler & Crutzen 1980, (8) Andreae & Merlet 2001, (9) Ito & Penner 2004, (10) van der Werf et al. 2004, (11) Vitousek et al. 1986, (12) Ramakrishna et al. 2003, (13) FAOSTAT 1990-2000

Table D1. Global numbers for benchmark with bisection and newton method







Figure D1. Global numbers for (a) vegetation carbon, (b) total soil carbon,(c) litter carbon, (d) harvested carbon rainfed tece, (e) harvested carbon rainfed rice.







Figure D2. Global sums for time series 4 of (a) harvested rainfed maize, (b) harvested rainfed soybean, (c) harvested irrigated tece, (d) harvested irrigated rice, (e) harvested irrigated maize, (f) harvested irrigated soybean.







Figure D3. Global sum for time series of (a) fire carbon, (b) establishment flux, (c) all area natural vegetation, (d) area tropical broadleveaved evergreen, (e) area tropical broadleaved raingreen, (f) area temperate needleleaved evergreen.







Figure D4. Global sum for time series of (a) area temperate broadleaved evergreen, (b) area temperate broadleaved summergreen, (c) area boreal needleleaved evergreen, (d) area broadleaved summergreen, (e) area boreal needleleaved summergreen, (f) area tropical C4 grass.







Figure D5. Global sum for time series of (a) area temperate C3 grass, (b) area polar C3 grass, (c) NPP, (d) heterotrophic respiration (e) evaporation, (d) transpiration .







Figure D6. Global sum for time series of (a) interception, (b) runoff, (c) tree cover fraction.







Difference maps: Run - Benchmark run 1991 - 2000

Figure D7. Difference maps of (a) vegetation carbon, (b) soil carbon, (c) litter carbon, (d) harvested carbon rainfed tece, (e) harvested carbon rainfed rice, (f) harvested carbon rainfed maize.







Figure D8. Difference maps of harvested carbon (a) rainfed soybean, (b) irrigated tece, (c) irrigated rice, (d) irrigated mize, (e) irrigated soybean, (f) fire carbon.







Figure D9. Difference maps of (a) establishment, (b) all natural vegetation, (c) frac. tropical broadleaved evergreen, (d) frac. tropical broadleaved raingreen, (e) frac. temperate needleleaved evergreen, (f) frac. temperate broadleaved evergreen.







Figure D10. Difference maps of (a) frac. temperate broadleaved summergreen, (b) boreal needleleaved evergreen, (c) boreal broadleaved summergreen, (d) frac. boreal needleleaved summergreen, (e) frac. tropical C4 grass, (f) frac. temperate C3 grass.







Figure D11. Difference maps of (a) frac. polar C3 grass, (b) NPP, (c) heterotrophic respiration, (d) evaporation, (e) transpiration, (f) interception.







Figure D12. Difference maps of (a) runoff and (b) tree cover fraction.





Author contributions. JN and RR performed the mathematical analysis, JN and WvB implemented and tested the new numerical methods,
 WvB conducted the simulation experiments and analysed the model performance and computation efficiency. JN wrote the paper, all authors contributed to the writing of the paper and discussion of the model study throughout to develop the work.

Competing interests. There are no competing interests.

Acknowledgements. The authors gratefully acknowledge the European Regional Development Fund (ERDF), the German Federal Ministry of Education and Research, and the Land Brandenburg for supporting this project by providing resources on the high-performance computer system at the Potsdam Institute for Climate Impact Research. We thank Marie Hemmen from PIK for her support in benchmarking the

235

LPJmL model.





References

Collatz, G.J., Ball, J.T., Grivet, C. and Berry, J.A.: Physiological and environmental regulation of stomatal conductance, photosynthesis and transpiration: a model that includes a laminar boundary layer. Agric. For. Meteorol., 54: 107-136, https://doi.org/10.1016/0168-1923(91)90002-8, 1991.

240

255

- Haxeltine, A., and Prentice, I. C.: BIOME3: An equilibrium terrestrial biosphere model based on ecophysiological constraints, resource availability, and competition among plant functional types, Global Biogeochemical Cycles, 10, 693-709, https://doi.org/10.1029/96GB023441996.
- Haxeltine, A., and Prentice, I. C.: A general model for the light-use efficiency of primary production, Functional Ecology, 10, 551-561,
 https://doi.org/10.2307/2390165, 1996.
 - Krinner, G., Viovy, N., Noblet-Ducoudré, N. d., Ogée, J., Polcher, J., Friedlingstein, P., Ciais, P., Sitch, S., and Prentice, I. C.: A dynamic global vegetation model for studies of the coupled atmosphere-biosphere system, Global Biogeochemical Cycles, 19, https://doi.org/10.1029/2003GB002199, 2005.
- Masson- Delmotte, V., P. Zhai, A. Pirani, S.L. Connors, C. Péan, S. Berger, N. Caud, Y. Chen, L. Goldfarb, M.I. Gomis, M. Huang, K.
 Leitzell, E. Lonnoy, J.B.R. Matthews, T.K. Maycock, T. Waterfield, O. Yelekçi, R. Yu, and B. Zhou (eds.). IPCC, 2021: Summary for Policymakers. In: Climate Change 2021: The Physical Science Basis. Contribution of Working Group I to the Sixth Assessment Report of the Intergovernmental Panel on Climate Change, Cambridge University Press. In Press. https://doi.org/10.1017/9781009157896
 - O'Neill, B. C. and Tebaldi, C. and van Vuuren, D. P. and Eyring, V. and Friedlingstein, P. and Hurtt, G. and Knutti, R. and Kriegler, E. and Lamarque, J.-F. and Lowe, J. and Meehl, G. A. and Moss, R. and Riahi, K. and Sanderson, B. M., The Scenario Model Intercomparison Project (ScenarioMIP) for CMIP6, Geoscientific Model Development, 9, 3461–3482, https://doi.org/10.5194/gmd-9-3461-2016, 2016.
- Pörtner, H.-O., Roberts, D.C., Poloczanska, E.S., Mintenbeck, K., Tignor, M., Alegría, A., Craig, M., Langsdorf, S., Löschke, S., Möller, V.,
 Okem, A. (eds.) IPCC, 2022: Summary for Policymakers In: Climate Change 2022: Impacts, Adaptation, and Vulnerability. Contribution of Working Group II to the Sixth Assessment Report of the Intergovernmental Panel on Climate Change, Cambridge University Press. In Press.
- 260 Prentice, I. C., Bondeau, A., Cramer, W., Harrison, S. P., Hickler, T., Lucht, W., Sitch, S., Smith, B., and Sykes, M. T.: Dynamic global vegetation modelling: quantifying terrestrial ecosystem responses to large-scale environmental change. In: Canadell, J.G., Pataki, D. E., and Pitelka L. F. (Eds.), Terrestrial Ecosystems in a Changing World, Springer, Springer Nature, https://doi.org/10.1007/978-3-540-32730-1, 2007.
- Reichstein, M., Camps-Valls, G., Stevens, B., Jung, M., Denzler, J., Carvalhais, N., and Prabhat: Deep learning and process understanding
 for data-driven Earth system science, Nature, 566, 195-204, https://doi.org/10.1038/s41586-019-0912-1, 2019.
- Schaphoff, S., Forkel, M., Müller, C., Knauer, J., von Bloh, W., Gerten, D., Jägermeyr, J., Lucht, W., Rammig, A., Thonicke, K., and Waha, K.: LPJmL4 - A dynamic global vegetation model with managed land, Part 2: Model evaluation, Geoscientific Model Development, 11, 1377-1403, 10.5194/gmd-11-1377-2018, 2018.
- Schaphoff, S., von Bloh, W., Rammig, A., Thonicke, K., Biemans, H., Forkel, M., Gerten, D., Heinke, J., Jägermeyr, J., Knauer, J., Langer-
- wisch, F., Lucht, W., Müller, C., Rolinski, S., and Waha, K.: LPJmL4 ? a dynamic global vegetation model with managed land ? Part 1: Model description, Geoscientific Model Development, 11, 1343-1375, https://doi.org/10.5194/gmd-11-1377-2018, 2018.





- Sitch, S., Prentice, I. C., Smith, B., Cramer, W., Kaplan, J., Lucht, W., Sykes, M., Thonicke, K., and Venevsky, S.: LPJ- a coupled model of vegetation dynamics and the terrestrial carbon cycle, Doctoral dissertation, Institute of Plant Ecology, Lund University, Lund, 213 pp., https://doi.org/10.5194/BG-11-2027-2014, 2000.
- 275 Schwarz, H. R., Köckler, N.: Numerische Mathematik, Ed.7, Vieweg+Teubner, Wiesbaden, https://doi.org/10.1007/978-3-8348-9282-9, 2009.
 - Smith, B., Prentice, I. C., and Sykes, M.: Representation of vegetation dynamics in modelling terrestrial ecosystems: comparison two contrasting approaches within European climate space, Global Ecology and Biogeography, https://doi.org/10.1046/j.1466-822X.2001.t01-1-00256.x, 2001.
- 280 Smith, B., Wårlind, D., Arneth, A., Hickler, T., Leadley, P., Siltberg, J., and Zaehle, S.: Implications of incorporating N cycling and N limitations on primary production in an individual-based dynamic vegetation model, Biogeosciences, 11, 2027-2054, https://doi.org/10.5194/bg-11-2027-2014, 2014.
 - von Bloh, W., Rost, S., Gerten, D., and Lucht, W.: Efficient parallelization of a dynamic global vegetation model with river routing, Environmental Modelling & Software, 25, 685-690, https://doi.org/10.1016/j.envsoft.2009.11.012, 2010.